Trust Your Robots! Predictive Uncertainty Estimation of Neural Networks with Sparse Gaussian Processes



A. Research Questions

A method for Neural Networks:

- Fast uncertainty estimation running on a real robotic system.
- Reliable uncertainty estimation as good as Gaussian Processes.

This will enable robotic introspection for improving robustness and safety!



B. Our Main Idea

We propose a predictive model:

- likely predictions.
- uncertainty estimates.

See figure below for illustrations





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Neural Networks for accurate most-

• Sparse Gaussian Processes for reliable



C. The Proposed Method

• Linearize Neural Networks:

$\widetilde{y} = J_f(x)\theta + \epsilon$

In a function space view, we can view this as a GP with the Neural Tangent Kernel.

Casting into sparse GPs:

$$\widetilde{y} = \sum_{m=1}^{M} g_m(x) \widetilde{f_m}(x) + \epsilon_m$$

$$\tilde{f}_m(\mathbf{x}) \sim \mathbf{GP}(\mathbf{0}, \frac{1}{\delta_m} \mathbf{J}_{\mathbf{f}_m}^{\mathrm{T}}(\mathbf{x}) \mathbf{J}_{\mathbf{f}_m}(\mathbf{x}))$$

Divide and conquer principle to improve scalability of GPs.

In this mixtures of experts model:

Generative model - scalability:

 $\begin{bmatrix} \widetilde{y}_m \\ \widetilde{f}_m \end{bmatrix} \sim N \left(0, \begin{bmatrix} K_m + \sigma_0 I \\ k_{m,*} \end{bmatrix} \right)$ $k_{*.m}$ *k*_{*m*,**},

• Predictive in Regression – closed form:

$$\Sigma_m = k_{m,**}$$
$$-k_{m,*}^T (K_m + \sigma_0 I)^{-1} k_{m,*} + \sigma_0 I$$

Predictive Classification – closed form:

$$p(c|z_m) = \left(\frac{Z_m}{\sqrt{1 + \lambda_{m,0}\Sigma_m(x^*)}}\right)$$

E. Main Results

The selected highlights are:

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• Real robot test:



F. Key Take-Aways

Summary of our contributions are:



paper

Scalability tested upto approx. two million data points, and support for distributed training.

performance and run-time.

Theory that connects neural networks to mixtures of GP experts. Ablation studies and comparisons in the paper!

A method to estimate predictive uncertainty of neural networks with sparse Gaussian Processes. Theory that connects neural networks to sparse Gaussian Processes -> practical algorithm.

code